UNIDEX 100

THM

REFERENCE DOCUMENT

OPTION MANUAL

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IDENTIFICATION

for

Unidex 100 Series
THM Option Manual

by

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# Table of Contents

<table>
<thead>
<tr>
<th>SECTION</th>
<th>PAGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>CHAPTER 1</td>
<td></td>
</tr>
<tr>
<td>INTRODUCTION</td>
<td></td>
</tr>
<tr>
<td>CHAPTER 2</td>
<td></td>
</tr>
<tr>
<td>GETTING STARTED</td>
<td></td>
</tr>
<tr>
<td>2.1</td>
<td>THM Interface Connections</td>
</tr>
<tr>
<td>2.2</td>
<td>Display Extension Bus Address</td>
</tr>
<tr>
<td>2.3</td>
<td>Initial THM Power Up</td>
</tr>
<tr>
<td>CHAPTER 3</td>
<td></td>
</tr>
<tr>
<td>PROGRAMMING THE THM</td>
<td></td>
</tr>
<tr>
<td>3.1</td>
<td>Reading Thumbwheel Data</td>
</tr>
<tr>
<td>3.2</td>
<td>Thumbwheel Sign</td>
</tr>
<tr>
<td>3.3</td>
<td>Execute</td>
</tr>
<tr>
<td>3.4</td>
<td>Program Example</td>
</tr>
<tr>
<td>CHAPTER 4</td>
<td></td>
</tr>
<tr>
<td>HARDWARE</td>
<td></td>
</tr>
<tr>
<td>4.1</td>
<td>Unidex 100 THM Option Location</td>
</tr>
<tr>
<td>4.2</td>
<td>THM Board Desriptions</td>
</tr>
<tr>
<td>4.2.1</td>
<td>THM Interface Board</td>
</tr>
<tr>
<td>4.2.2</td>
<td>Thumbwheel Board</td>
</tr>
<tr>
<td>4.3</td>
<td>THM Interface Connections</td>
</tr>
<tr>
<td>4.4</td>
<td>THM Interface Board Jumpers</td>
</tr>
<tr>
<td>4.5</td>
<td>THM Interface and Thumbwheel Board Connections</td>
</tr>
<tr>
<td>4.5.1</td>
<td>Interface Board (P1) to UNIDEX 100 Cable</td>
</tr>
<tr>
<td>4.5.2</td>
<td>Interface (P2,P3) to THM (P1) Cables</td>
</tr>
<tr>
<td>SECTION</td>
<td>PAGE</td>
</tr>
<tr>
<td>---------</td>
<td>------</td>
</tr>
<tr>
<td>4.5.3</td>
<td>Thumbwheel Board Execute Connection (P2)</td>
</tr>
<tr>
<td>4.6</td>
<td>THM Interface Board Power Requirements</td>
</tr>
</tbody>
</table>
# List of Figures

<table>
<thead>
<tr>
<th>FIGURE</th>
<th>Title</th>
<th>PAGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>4-1</td>
<td>Mounting of THM Interface Board to U100 Control Board............... 4-2</td>
<td></td>
</tr>
<tr>
<td>4-2</td>
<td>THM Interface Board .................................................................. 4-4</td>
<td></td>
</tr>
<tr>
<td>4-3</td>
<td>THM Thumbwheel Board .................................................................. 4-5</td>
<td></td>
</tr>
<tr>
<td>4-4</td>
<td>THM PC Board Connections ................................................................ 4-6</td>
<td></td>
</tr>
<tr>
<td>4-5</td>
<td>Pin Connections for P2 or P2 of Interface Bd. &amp; P1 of THM Bd. . 4-8</td>
<td></td>
</tr>
<tr>
<td>4-6</td>
<td>SPST Normally Open Switch ................................................................ 4-8</td>
<td></td>
</tr>
</tbody>
</table>
CHAPTER 1: INTRODUCTION

The THM option for the UNIDEX 100 includes:

- Six-digit Thumbwheel Board
- Six-digit Interface Board
- Thumbwheel Interface Cable

The UNIDEX 100 Six-digit Thumhbheel Board, referred to as the Thumbwheel Board, is a six-digit (plus sign) thumbwheel assembly. The Six-digit Interface Board, referred to as the Interface Board, reads the thumbwheels and provides this information to the UNIDEX 100 upon request. The Thumbwheel Interface Cable connects the Thumbwheel Board to the Interface Board. The THM permits the user to enter data such as distance, speed, or number of cycles into parts program variables. The interface card plugs onto the expansion bus and is housed in a 6.25" W x 3.75" H x 2.25" D box that can be removed for panel mounting. The THM derives its power from the UNIDEX 100.

Before continuing, it is best that the user reviews the *Unidex 100 Operation & Technical Manual* or has some understanding of how the UNIDEX 100 works.
CHAPTER 2: GETTING STARTED

This chapter includes information pertaining to the initial setup for the THM option. Included is information describing the interface connections, THM parameter setup, and the initial THM power up. For information on safety considerations, preliminary troubleshooting, and customer assistance, please refer to Chapter 5 (Hardware) of the Unidex 100 Operation & Technical Manual.

2.1: THM Interface Connections

After mounting the thumbwheel option boards (see Chapter 4 on Hardware) it is necessary to make the required connections to the thumbwheel option boards.

The THM uses a 50-pin ribbon cable (maximum recommended cable length of 10 feet) with a connector at each end. One end of the ribbon cable connects to a locking header "P2 or P3" that protrudes from the front of the UNIDEX 100 while the other end connects to P1 of the Thumbwheel Board. To establish the power connection, P1 of the THM Interface Board connects to the Extension Bus Connector P5 of the UNIDEX 100 Control Board (refer to Chapter 4 for additional information).
2.2: Display Extension Bus Address

The six-digit display is a write only device that gets programmed with port variables (PV). The default display extension bus beginning address is 0xE000. The user may change this address using the DIP switch, SW1 (located on the THM Interface Board).

<table>
<thead>
<tr>
<th>Base Address</th>
<th>SW1-1</th>
<th>SW1-2</th>
<th>SW1-3</th>
<th>SW1-4</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xE000</td>
<td>on</td>
<td>on</td>
<td>on</td>
<td>on</td>
</tr>
<tr>
<td>0xE010</td>
<td>off</td>
<td>on</td>
<td>on</td>
<td>on</td>
</tr>
<tr>
<td>0xE020</td>
<td>on</td>
<td>off</td>
<td>on</td>
<td>on</td>
</tr>
<tr>
<td>0xE030</td>
<td>off</td>
<td>off</td>
<td>on</td>
<td>on</td>
</tr>
<tr>
<td>0xE040</td>
<td>on</td>
<td>on</td>
<td>off</td>
<td>on</td>
</tr>
<tr>
<td>0xE050</td>
<td>off</td>
<td>on</td>
<td>off</td>
<td>on</td>
</tr>
<tr>
<td>0xE060</td>
<td>on</td>
<td>off</td>
<td>off</td>
<td>on</td>
</tr>
<tr>
<td>0xE070</td>
<td>off</td>
<td>off</td>
<td>off</td>
<td>on</td>
</tr>
<tr>
<td>0xE080</td>
<td>on</td>
<td>on</td>
<td>on</td>
<td>off</td>
</tr>
<tr>
<td>0xE090</td>
<td>off</td>
<td>on</td>
<td>on</td>
<td>off</td>
</tr>
<tr>
<td>0xE0A0</td>
<td>on</td>
<td>off</td>
<td>on</td>
<td>off</td>
</tr>
<tr>
<td>0xE0B0</td>
<td>off</td>
<td>off</td>
<td>on</td>
<td>off</td>
</tr>
<tr>
<td>0xE0C0</td>
<td>on</td>
<td>on</td>
<td>off</td>
<td>off</td>
</tr>
<tr>
<td>0xE0D0</td>
<td>off</td>
<td>on</td>
<td>off</td>
<td>off</td>
</tr>
<tr>
<td>0xE0E0</td>
<td>on</td>
<td>off</td>
<td>off</td>
<td>off</td>
</tr>
<tr>
<td>0xE0F0</td>
<td>off</td>
<td>off</td>
<td>off</td>
<td>off</td>
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</tbody>
</table>

2.3: Initial THM Power Up

By now, the user should have completely connected the THM option. Turn on power (allowing approximately 10 seconds for the UNIDEX 100 to initialize). The THM option does not provide any status indication after being powered up. The user must verify that the THM option is operational. To do this it is necessary to read the thumbwheel data using the proper PV address (see Chapter 3 on programming the THM).
CHAPTER 3: PROGRAMMING THE THM

There are four THM locations that the user can program. These are as follows:

0xE0*0 - THM 1 Data (P2 of Thumbwheel Interface Board)
0xE0*1 - THM 1 Sign and Execute (P2 of Thumbwheel Interface Board)
0xE0*2 - THM 2 Data (P3 of Thumbwheel Interface Board)
0xE0*3 - THM 2 Sign and Execute (P3 of Thumbwheel Interface Board)

---

NOTE: The asterisk denotes a base address number. See the THM Extension Bus Address in Chapter 2.

3.1: Reading Thumbwheel Data

The UNIDEX 100 reads the Thumbwheel Data with a PV variable addressed to the Thumbwheel data port. There are two thumbwheel data ports available. The Thumbwheel #1 data port reads thumbwheels connected to P2 of the Thumbwheel Interface Board and uses an address of 0xE0*0 (* is dependent on base address, see Section 2.2). The Thumbwheel #2 data port reads thumbwheels connected to P3 of 0xE0*2 (* is dependent on base address, see Section 2.2).

Before it is possible to read the thumbwheel data it is necessary to latch it using the thumbwheel execute function (see Section 3.3). The system returns thumbwheel data in a BCD format. However the user may convert this data to an integer format by using the CBI command. For example: FV:1=CBI(PV=0xE010) that reads the Thumbwheel data port #1, converts the data to an integer format, and places the value in variable FV:1 in the above example.

Note that the base address is equal to 0xE010.
3.2: Thumbwheel Sign

A separate data address reads the Thumbwheel Sign. Like the data there are two sign addresses: Thumbwheel #1 and Thumbwheel #2. To obtain Thumbwheel #1 (P2 of the Interface Board) it is necessary to read the address 0xE0*1 (* determined by the base address, see Section 2-2) where Thumbwheel #2 (P3 of the Interface Board) requires that address 0xE0*3 be read to obtain its sign.

Bit #23 holds the sign status and changes its setting to a one if the sign is negative. When the user requires a negative data value they can determine the sign and negate the data by testing this bit. For example: BV:1=PV:0xE001 and 0x800000, IF(BV:1 EQ 0x800000) which reads the Thumbwheel #1 sign and tests the sign for a negative. The status of the sign gets sent to the BV:1 variable.

Note, in the above example, that the base address is equal to 0xE000.

3.3: Execute

The execute latches the data and sign into the Thumbwheel Interface Board upon pressing the execute. The execute status is bit #16 and uses the same address as the sign. Bit #16 is high upon pressing the execute. For example IF(PV=0xE001 AND 0x010000) which checks for a Thumbwheel #1 execute switch closure.

Note, in the above example, that the base address is equal to 0xE001.
3.4: Program Example

In some cases the user may wish to enter the length necessary for cut-to-length applications. To do this, the length must be an input variable. The variable value can come from a host controller, a set of thumbwheels, or an operator keypad/display unit. The optional THM is a six-digit thumbwheel addressable on the UNIDEX 100 Expansion Bus. The location for this thumbwheel is at E010 hex. The user units are machine steps. For an example of how this works refer to the following program.

```
BEGIN
BV:1=PV:0xE011 AND 0x10000
WHL(BV:1 NE 0x10000)
  BV:1=PV:0xE011 AND 0x10000
ENDWHL
FV:1=CBI(PV:0xE010)
IF(PV:0xE011 AND 0x800000)
  FV:1=-1*FV:1
ENDIF
D(FV:1)
V(6000)
GO
END
```

; Start the program.
; BV:1 will equal 0x10000 when depressed.
; Wait until the button is depressed.
; BV:1 will equal 0x10000 when depressed.
; End the while loop.
; Set FV:1 equal to the CBI of variable PV:0xE010
; If sign is negative, FV:1 will be negated.
; Set the variable FV:1 to negative.
; End the IF statement.
; Set the distance equal to the value of the FV:1
; variable.
; Set the velocity equal to 6000.
; Start the move.
; End the program.
CHAPTER 4: HARDWARE

In this Chapter you will find information concerning the THM boards and related hardware. It will provide information on both electrical and mechanical features.

4.1: UNIDEX 100 THM Option Location

There are two boards supplied with UNIDEX 100's THM option: Interface Board and Thumbwheel Board. The UNIDEX 100 THM Interface Board mounts to the UNIDEX 100 Control Board with four #4-40 x 3/4" standoffs. These standoffs get screwed into the female studs located behind the mounting holes on the control board. There are two #4-40 x 1/4" screws that go through the mounting holes at the front of the THM Interface Board. Two #4-40 x 1/2" screws get screwed into the remaining two standoffs through the holes in the DIN connector. For an example on how to mount the THM Interface Board to the UNIDEX 100 Control Board, see Figure 4-1 on the following page.

As for the UNIDEX 100 THM Six-digit Thumbwheel Board, the user can mount it in one of two ways: remotely or housed in the standard plastic enclosure.
Figure 4-1: Mounting of THM Interface Board to UNIDEX 100 Control Board

NOTE: This option can be field installed, however it requires option wiring (consult factory). The UNIDEX 100 Control Board can mount 2 option boards.
4.2: THM Board Descriptions

The THM option consists of two boards: Interface Board and Thumbwheel Board. The following sections describe each one in detail.

4.2.1: THM Interface Board

The THM Interface Board is a 3U size board that provides the UNIDEX 100 with the capability of reading up to two thumbwheel boards or simulated thumbwheel interfaces (user may simulate the Thumbwheel Board using their own interface). Thumbwheel #1 uses P2 as its interface port while Thumbwheel #2 uses P3 for its port.

All the thumbwheel interface ports (P2 and P3) signal inputs use logic levels of +5V and 0 volts; however, it is possible to drive these inputs using open collector devices due to the 10K pull-up resistors. By using the execute input the user can latch the six-digit BCD coded inputs.

The UNIDEX 100 obtains data from the Interface Board through the Extension Bus connection (P1). To access the board it is necessary to use the proper address, SW1 (Base Address, Section 2.2). This section partially determines what address to use. Figure 4-2 shows the THM Interface Board and component functions.
Figure 4-2: THM Interface Board
4.2.2: Thumbwheel Board

The THM Thumbwheel Board is a data entry board that connects to the UNIDEX 100 through the THM Interface Board. This board contains six-digit BCD thumbwheels, a sign thumbwheel, an execute connector (P2), and the interface connector (P1). The six-digit thumbwheels are active low, which means that the associated BCD line connects to COM to activate that line. The Sign Thumbwheel also makes connection to common when there is a closed contact. The execute button, connected to P2, causes the execute line to connect to common upon pressing the button.

The P1 connection is a 50-pin connector used to connect the THM Thumbwheel Board to the THM Interface Board (see Section 4.5.2).

Figure 4-3: THM Thumbwheel Board
4.3: THM Interface Connections

To connect the UNIDEX 100’s THM Interface Board and the Thumbwheel Board it is necessary to connect the 50-pin ribbon cable assembly between the Interface and Thumbwheel boards. See Figure 4-4 below.

Figure 4-4: THM PC Board Connections
4.4: THM Interface Board Jumpers

There is one jumper on the THM Interface board. This jumper allows the user to interrupt the UNIDEX 100 upon pressing the Execute push-button. If JP1 is in the 1-2 position upon pressing the Execute push-button an interrupt occurs on the UNIDEX 100. When JP1 is in the 2-3 position, the UNIDEX 100 does not generate an interrupt.

The following is the recommended and standard jumper position:

JP1 - 2-3 (Upon pressing the Execute button no interrupt occurs)

4.5: THM Interface and Thumbwheel Board Connections

The THM option requires several connections. These include:

P1 - Interface Board (64-pin)
P2 - Interface Board (50-pin)
P3 - Interface Board (50-pin)
P1 - Thumbwheel Board (50-pin)
P2 - Thumbwheel Board (2-pin)

4.5.1: Interface Board (P1) to UNIDEX 100 Cable

Connecting a cable between P1 on the Interface Board and P5 on the UNIDEX 100 Control Board establishes the power connection between the THM Thumbwheel option and the UNIDEX 100. This cable is a 64-pin cable.
4.5.2: Interface (P2, P3) to THM (P1) Cables

P1 on the Thumbwheel Board and P2 or P3 on the Interface Board connect the thumbwheel boards to the Interface Board. A 50-pin ribbon cable, with the mate to connectors P1 and P2 or P3, establishes the link between the Thumbwheel Board and Interface Board. The total cable length should not exceed 10 feet. To determine the pin connections for these connectors refer to Figure 4-5.

Figure 4-5: Pin Connections for P2 or P3 of Interface Board and P1 of Thumbwheel Board
4.5.3: Thumbwheel Board Execute Connection (P2)

The Thumbwheel Board contains a 2-pin connector (P2) used for an Execute push-button. These pins should be connected to a SPST normally open push-button switch (see Figure 4-6).

![Diagram of P2 connection]

Note: Pin P2-1 is pulled high with 10K Ohm resistor
Pin P2-2 is connected to common.

Figure 4-6: SPST Normally Open Switch

4.6: THM Interface Board Power Requirements

The THM Interface Board requires +5 volts, all of which P1 provides. By no means should this voltage be greater than 5.25 volts or less than 4.75 volts. Voltages not falling within the operating range may cause damage or operational failure.
INDEX

2-pin Connector, 4-9
50-pin Connector, 4-5
50-pin Ribbon Cable, 2-1, 4-8
64-pin Cable, 4-7

A
Accessing Thumbwheel #1 Address, 3-2
Accessing Thumbwheel #2 Address, 3-2
Activating the BCD Line, 4-5
Active Low Thumbwheels, 4-5
Address Selection, 4-3
Applying Power, 2-2

B
Base Addresses, 2-2
BCD Coded Inputs, 4-3
BCD Line, 4-5
BCD Thumbwheel Data Format, 3-1
Bits, 3-2

C
CBI Command, 3-1
Chassis, 1-1
Connecting the THM Interface Board, 4-6
Connections from P2 or P2 Interface to THM P1
  Cable, 4-8
Connections from U100 Cable to P1 of Interface
  Board, 4-7
Converting Data Formats, 3-1
Customer Assistance, 2-1
Cut-to-length Applications, 3-3

D
Damage, 4-9
Data Entry, 1-1
Data Latching, 3-2
DIN Connector, 4-1
DIP Switch, SW1, 2-2
Display Default Address, 2-2
Display Extension Bus Address, 2-2
Driving Inputs, 4-3

E
Electrical Features, 4-1
Execute Address, 3-2
Execute Button, 4-5
Execute Connector, 4-5
Execute Function, 3-1, 3-2
Execute Push-Button, 3-1, 4-7, 4-9
Execute Switch Closure, 3-2
Expansion Bus, 1-1, 3-3
Extension Bus Address, 2-2, 3-1
Extension Bus Connector, 2-1, 4-3

F
Field Installing the Option, 4-2

H
Hardware, 4-1
Host Controller, 3-3

I
Initial THM Power Up, 2-2
Initialization Time, 2-2
Input Variable, 3-3
Integer Thumbwheel Data Format, 3-1
Interface Board, 4-3
Interface Connections, 2-1
Interface Connector, 4-5
Interface Port for Thumbwheel #1, 4-3
Interface Port for Thumbwheel #2, 4-3
Interrupting the UNIDEX 100, 4-7

J
Jumpers, 4-7

L
Latching Six-digit BCD Coded Inputs, 4-3
Latching the Data, 3-2
Latching the Sign, 3-2
Latching Thumbwheel Data, 3-1
Linking Thumbwheel Board to Interface Board, 4-8
Location of Interface Card, 1-1
Locking Header, 2-1

M
Making Power Connection, 4-7
Making Thumbwheel Data Readable, 3-1
Mechanical Features, 4-1
INDEX

Mounting of THM Interface Board to UNIDEX 100
Control Board, 4-2
Mounting the Option Boards, 4-1
Mounting the THM Board, 2-1

O

Open Collector Devices, 4-3
Operational Failure, 4-9
Operator Keypad/Display Unit, 3-3
Option Mounting, 4-1
Option Wiring, 4-2

P

P1, 2-1, 4-3, 4-5, 4-7, 4-8, 4-9
P2, 2-1, 3-1, 3-2, 4-3, 4-5, 4-8, 4-9
P3, 2-1, 3-1, 3-2, 4-3, 4-8
P5, 2-1, 4-7
Panel Mounting, 1-1
Parameter Setup, 2-1
Parts Program Variables, 1-1
Pin Connections for P2 or P3 of Interface Board and
P1 of Thumbwheel Board, 4-8
Port Variables, 2-2
Power Source of THM, 1-1
Power Up, 2-1, 2-2
Precautionary Measures, 2-1
Program Example, 3-3
Programming Locations for THM, 3-1
Programming the Six-digit Display, 2-2
Programming the THM, 2-2
PV Addresses, 2-2
PV Variables, 2-2, 3-1

R

Reading the Thumbwheel #1 Sign, 3-2
Reading Thumbwheel Data, 2-2, 3-1
Recommended Jumper Position, 4-7
Related Hardware, 4-1

S

Safety Considerations, 2-1
Service & Repair, 2-1
Setup, 2-1
Shipping Contents, 1-1
Sign Addresses, 3-2
Thumbwheel #1, 3-2
Thumbwheel #2, 3-2

Sign Latching, 3-2
Sign Status Bits, 3-2
Sign Status Storage, 3-2
Sign Thumbwheel, 4-5
Simulating the Thumbwheel, 4-3
Six-digit BCD Thumbwheels, 4-5
Six-digit Display, 2-2
Six-digit Display Programming, 2-2
Six-digit Interface Board, 1-1
Six-digit Thumbwheel Board, 4-1
Remote Mounting, 4-1
Standard Plastic Enclosure Housing, 4-1
SPST Normally Open Switch, 4-9
Standard Jumper Position, 4-7
SW1 DIP Switch, 2-2
Switch Closure, 3-2
System Initialization, 2-2

T

Testing Sign Status Bits, 3-2
THM 1 Data, 3-1
THM 2 Data, 3-1
THM 2 Sign and Execute, 3-1
THM Board Descriptions, 4-1, 4-3
THM Electrical Features, 4-1
THM Extension Bus Address, 3-1
THM Interface Board, 4-3, 4-4
THM Interface Board Jumpers, 4-7
THM Interface Board Power Requirements, 4-9
THM Interface Connections, 2-1, 4-6
THM Mechanical Features, 4-1
THM Mounting Example, 4-1
THM Option Mounting, 4-1
THM Parameter Setup, 2-1
THM PC Board Connections, 4-6
THM Power Source, 1-1
THM Power Up, 2-1, 2-2
THM Programming Locations, 3-1
THM Related Hardware, 4-1
THM Setup, 2-1
THM Thumbwheel Board, 4-5
Thumbwheel #1, 4-3
Thumbwheel #1 Data Port, 3-1
Thumbwheel #1 Execute Switch Closure, 3-2
Thumbwheel #2 Data Port, 3-1
Thumbwheel Board, 4-3, 4-5
Thumbwheel Board Execute Connector (P2), 4-9
Thumbwheel Data, 3-1
Thumbwheel Data Port, 3-1
Thumbwheel Data Port #1, 3-1
Thumbwheel Interface Cable, 1-1
Thumbwheel Sign, 3-2
INDEX

U
UNIDEX 100 Control Board, 2-1, 4-1, 4-2
UNIDEX 100 Expansion Bus, 3-3
UNIDEX 100 Six-digit Thumbwheel Board, 1-1
UNIDEX 100 THM Interface Board, 4-1
User Programmable Locations, 3-1
User Supplied Interface, 4-3
User Units, 3-3

V
Verifying Proper Installation, 2-2
Voltages, 4-9

W
Warm-up Time, 2-2